

**Notes:**

Make sure that the PCB grounds do not touch the inside of the case and isolate the TO-220 voltage regulators from the end panels of the case with silicon insulators and use plastic isolators on the metal screws.

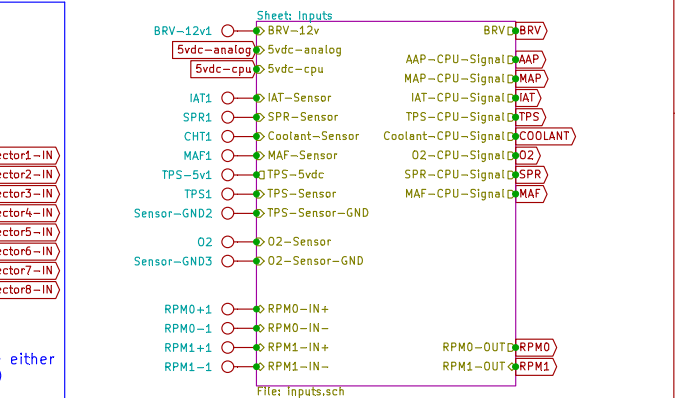
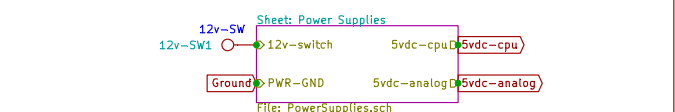
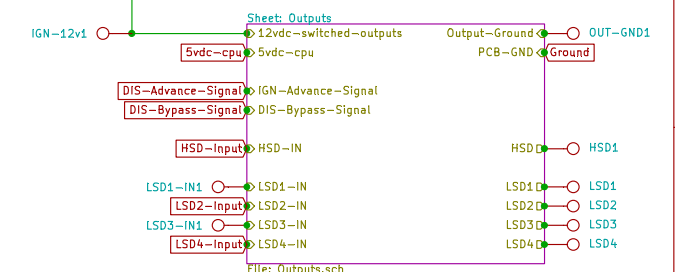
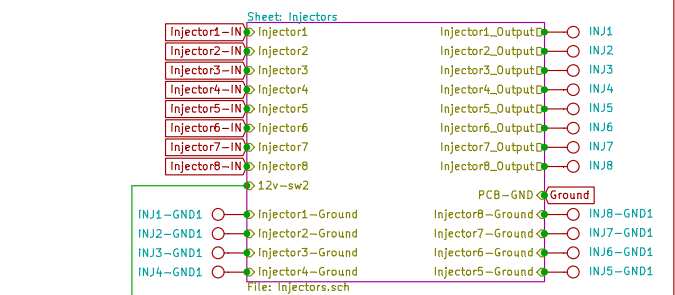
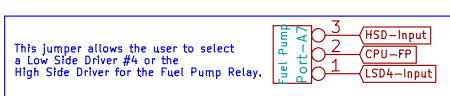
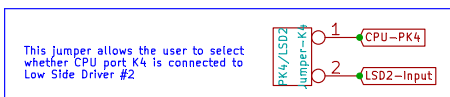
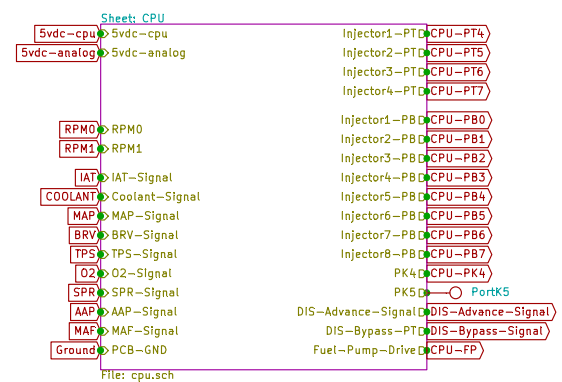
5vdc-cpu = VDD

5vdc-analog = VCC

Components that are missing from design changes:

C45, C46, C50, D3, D32, R14, R15, R56, R59, R60, R61, R62, R64, R65, R79, R85, R86, R93, R94, R96, R97, R98, R99, U5, U10

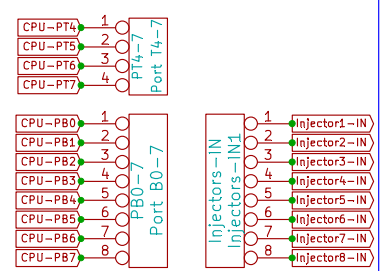
This PCB is intended to be used with either the specified Context Engineering enclosure or retro-fitted into a factory ECU enclosure.



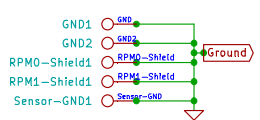
For 6/8 cylinder using Port T with current code, run Jumper wires from:  
 PT4-7 pin 1 to PB0-7 pin 1 = Bank 1  
 PT4-7 pin 2 to PB0-7 pin 3 = Bank 2  
 PT4-7 pin 3 to PB0-7 pin 5 = Bank 3  
 PT4-7 pin 4 to PB0-7 pin 7 = Bank 4

**AND DO THE FOLLOWING**  
 For 6/8 cylinder using Port T with current code jumper from:  
 (can be tie-bar shorting jumper if you installed a 0.100" pin header for Injectors-IN)  
 Injectors-IN pin 1 to pin 2  
 Injectors-IN pin 3 to pin 4  
 Injectors-IN pin 5 to pin 6  
 Injectors-IN pin 7 to pin 8

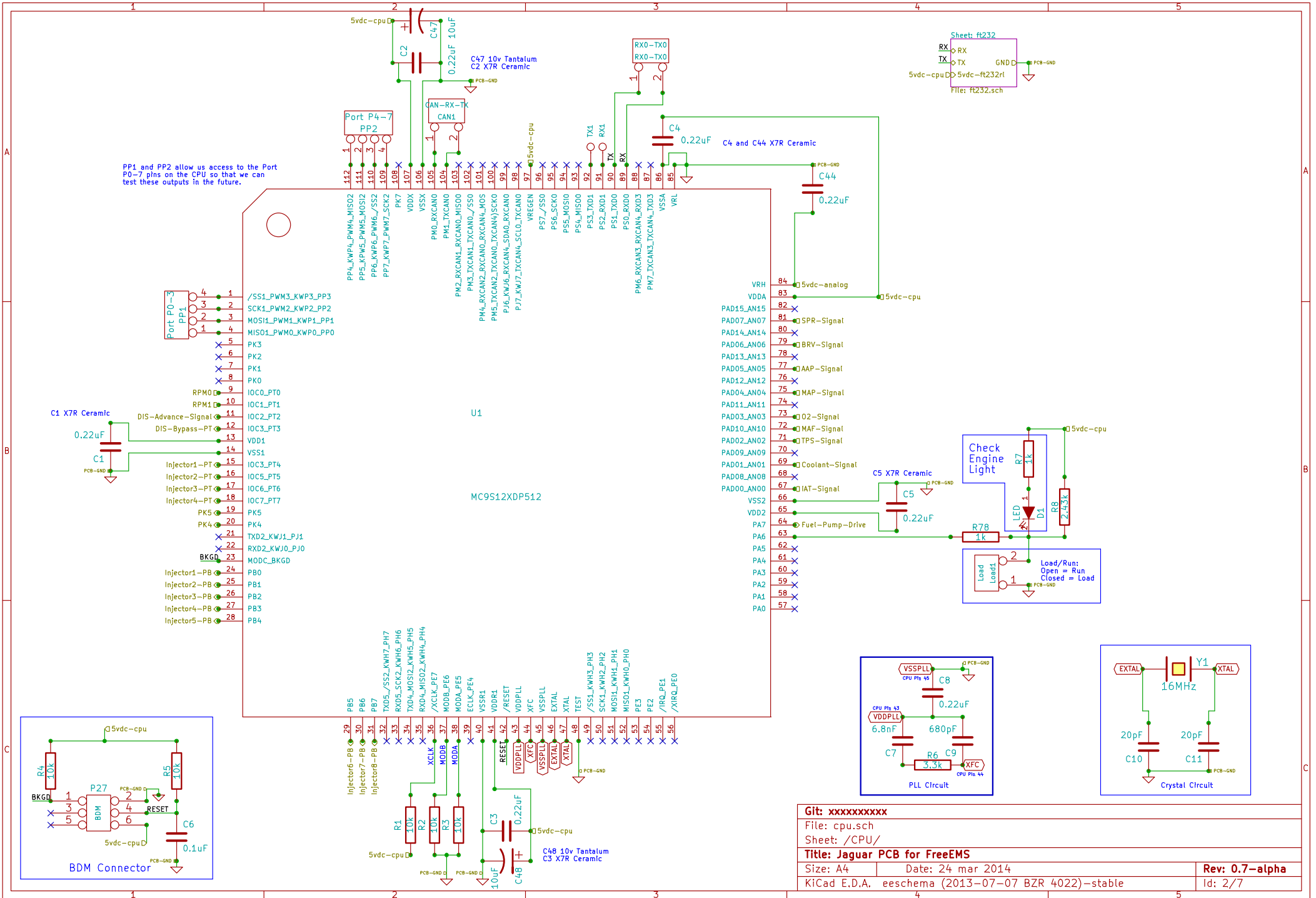
To use Port B with future XGATE code, run jumper wires from:  
 P33 to P34 pin for pin and do not connect anything to P20.  
 i.e.  
 PB0-7 pin 1 to Injectors-IN pin 1  
 PB0-7 pin 2 to Injectors-IN pin 2  
 PB0-7 pin 3 to Injectors-IN pin 3  
 PB0-7 pin 4 to Injectors-IN pin 4  
 PB0-7 pin 5 to Injectors-IN pin 5  
 PB0-7 pin 6 to Injectors-IN pin 6  
 PB0-7 pin 7 to Injectors-IN pin 7  
 PB0-7 pin 8 to Injectors-IN pin 8



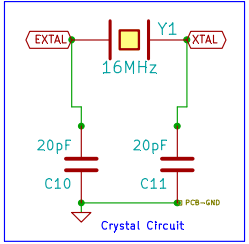
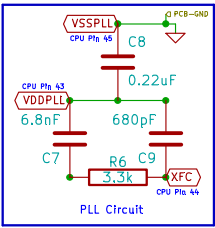
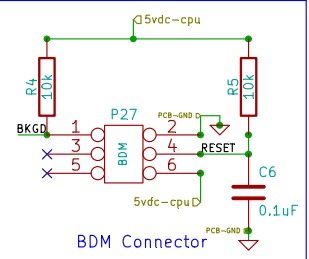
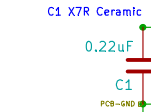
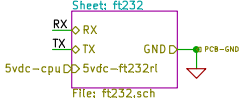
PT4-7 and PB0-7 allow for selection to use either Port T (4 cpu outputs:current code) or Port B (8 cpu outputs:future XGATE code)



<b>Git: xxxxxxxxx</b>	
File: Jaguar.sch	
Sheet: /	
<b>Title: Jaguar PCB for FreeEMS</b>	
Size: A4	Date: 24 mar 2014
KiCad E.D.A. eschema (2013-07-07 BZR 4022)-stable	<b>Rev: 0.7-alpha</b>
	Id: 1/7



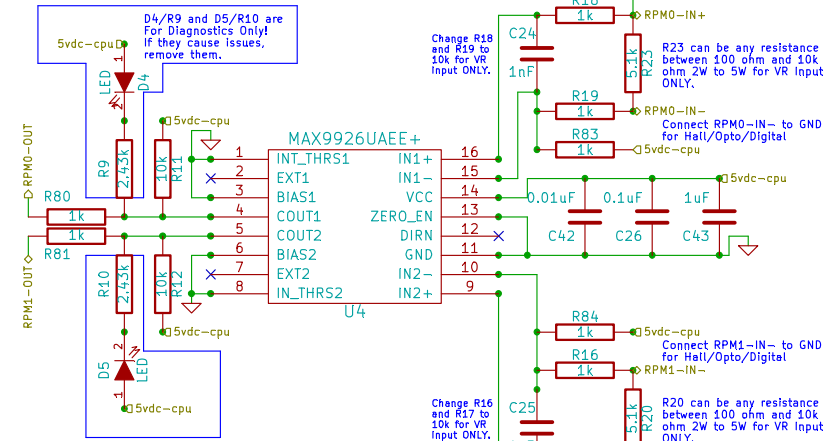
PP1 and PP2 allow us access to the Port P0-7 pins on the CPU so that we can test these outputs in the future.



Git: xxxxxxxxxx		
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Sheet: /CPU/		
<b>Title: Jaguar PCB for FreeEMS</b>		
Size: A4	Date: 24 mar 2014	Rev: 0.7-alpha
KiCad E.D.A. eschema (2013-07-07 BZR 4022)-stable		Id: 2/7

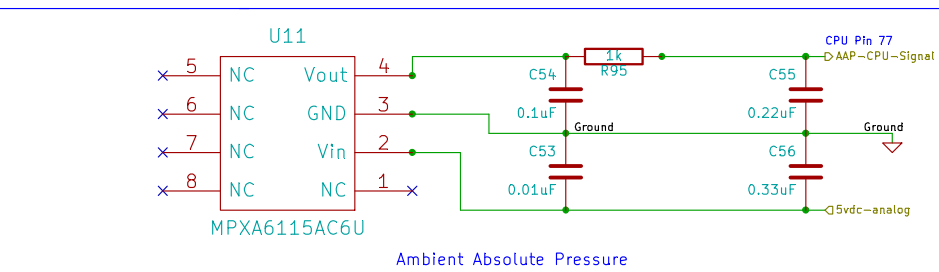


For GM DIS and Ford EDIS connect RPM0-IN- and RPM1-IN- to ground.  
 For Ford EDIS do not connect RPM1-IN+ to anything, it isn't needed unless you have a cam sensor for semi-sequential or sequential injection. R16, R17, C25, R10, R12 and D5 are not needed for the EDIS system.  
 R20 and 23 are only to be used with VR Inputs, do not populate these components for GM DIS or Ford EDIS systems.

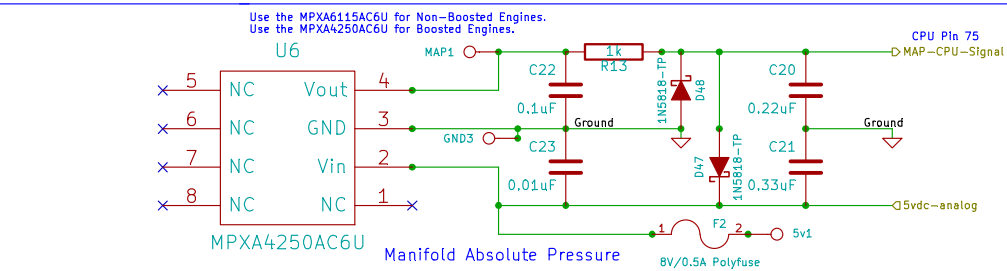


NOTE: MAX9926 should be configured as Mode A2 for both VR and Hall/Opto/Digital Inputs.  
 RPM0-IN- and RPM1-IN- should be held at 2.5vdc for Hall/Opto/Digital inputs.  
 R16, R84, R19 and R83 accomplish this by setting up a voltage divider circuit.  
 For VR inputs, R18, R19, R16 and R17 need to be 10k resistors.

Crankshaft and Camshaft Inputs

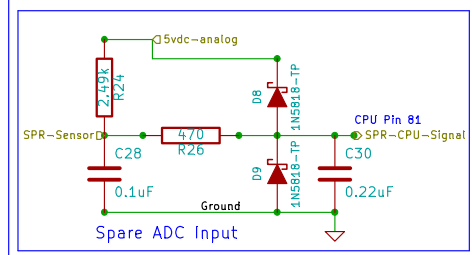


Ambient Absolute Pressure

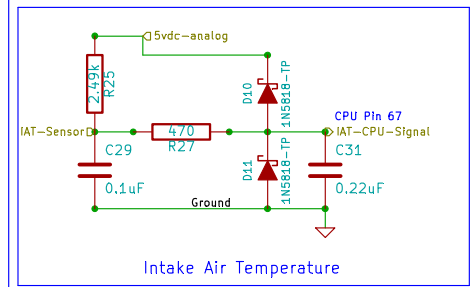


Manifold Absolute Pressure

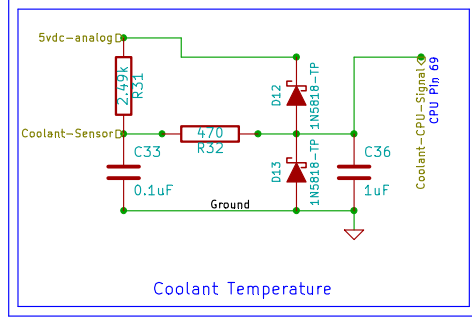
R24, R25 and R31 (2.49k) can be replaced if using sensors other than GM temperature sensors; For FORD Sensors; use 27.4k 0.1% Metal Film resistors; for MOPAR Sensors; use 9.1k 0.1% Metal Film resistors or use 2.43k 0.1% Metal Film resistors (best for most cases). Be sure to use FreeTherm to adjust the values in the FreeEMS code for the best accuracy regardless of which value resistors you use!



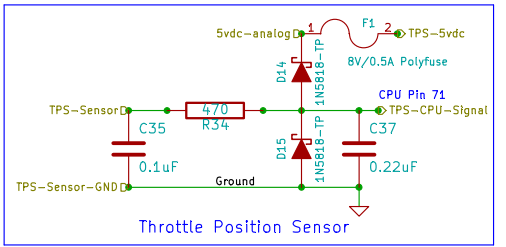
Spare ADC Input



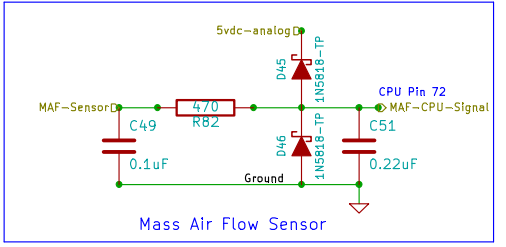
Intake Air Temperature



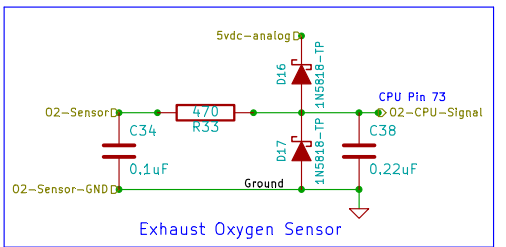
Coolant Temperature



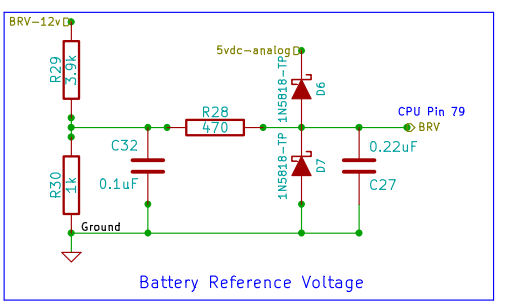
Throttle Position Sensor



Mass Air Flow Sensor



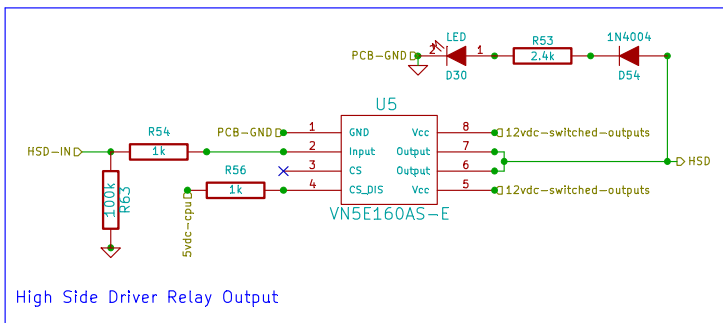
Exhaust Oxygen Sensor



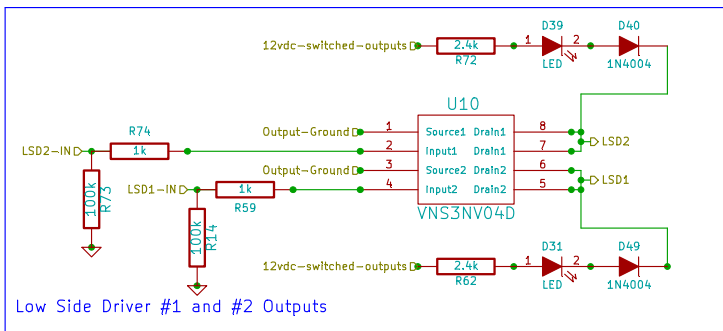
Battery Reference Voltage

D47 and D48 are only populated if you are using an external MAP sensor. Do not populate these locations if you are using the on-board sensor.  
 Do not populate C23 and C21 if you are using an external MAP sensor.  
 Change R13 value from 1k to 470 ohm if you are using an external MAP sensor.

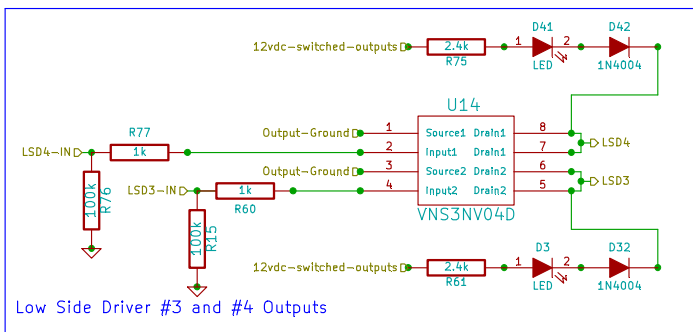
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File: inputs.sch	
Sheet: /Inputs/	
Title: Jaguar PCB for FreeEMS	
Size: A4	Date: 24 mar 2014
KiCad E.D.A. eschema (2013-07-07 BZR 4022)-stable	
Rev: 0.7-alpha	
Id: 4/7	



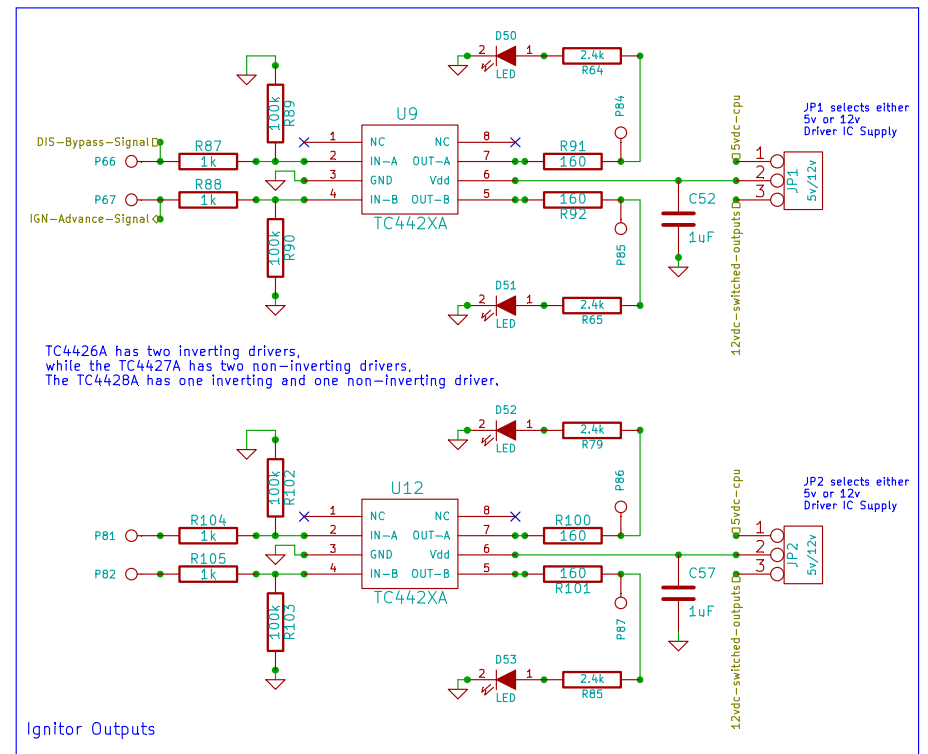
High Side Driver Relay Output



Low Side Driver #1 and #2 Outputs



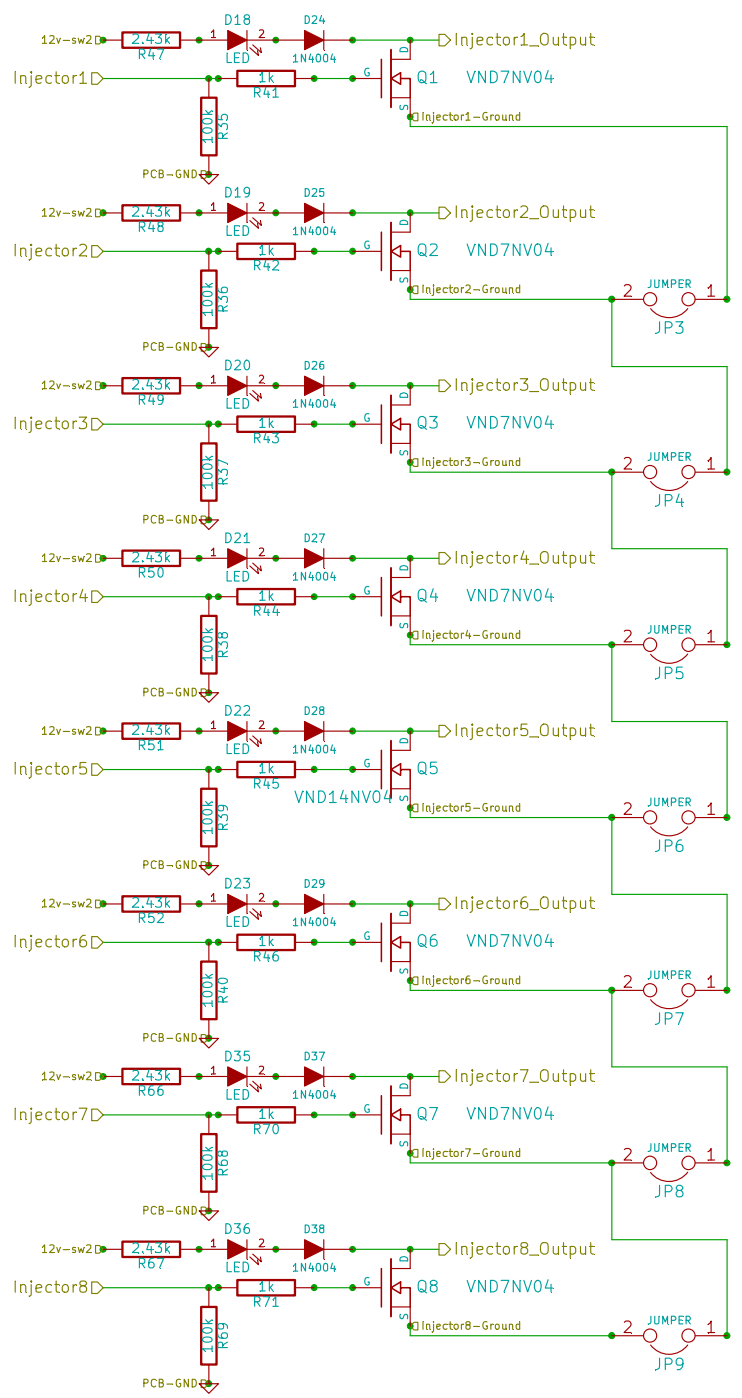
Low Side Driver #3 and #4 Outputs



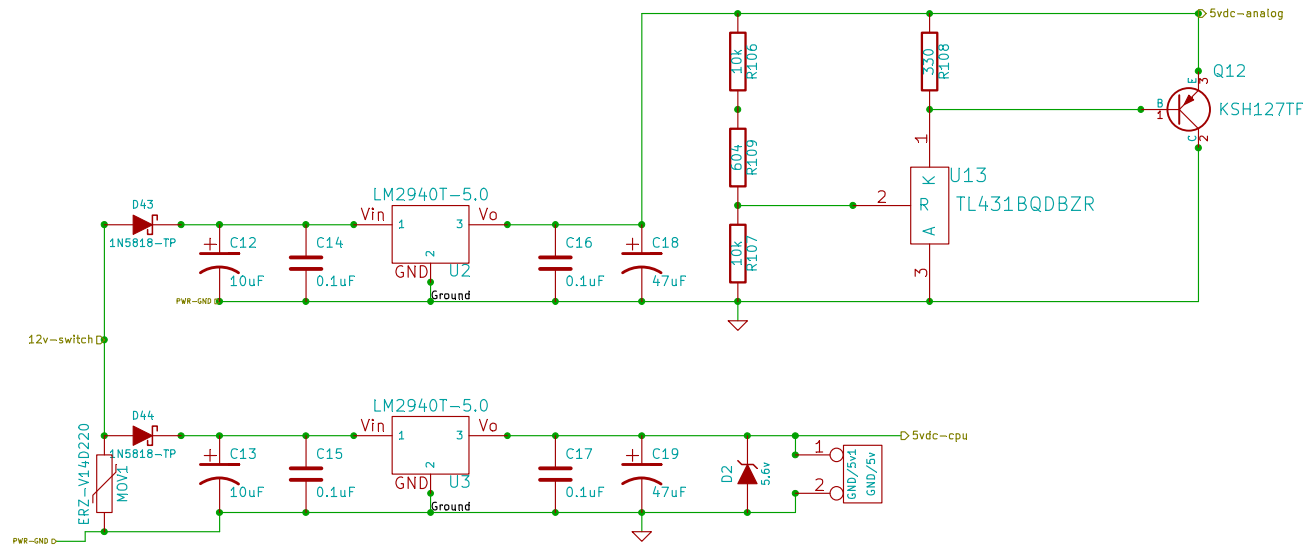
TC4426A has two inverting drivers, while the TC4427A has two non-inverting drivers. The TC4428A has one inverting and one non-inverting driver.

Ignitor Outputs

Git: xxxxxxxxx		
File: Outputs.sch		
Sheet: /Outputs/		
Title: Jaguar PCB for FreeEMS		
Size: A4	Date: 24 mar 2014	Rev: 0.7-alpha
KiCad E.D.A. eschema (2013-07-07 BZR 4022)-stable		Id: 5/7



Git: xxxxxxxxx		
File: Injectors.sch		
Sheet: /Injectors/		
Title: Jaguar PCB for FreeEMS		
Size: A4	Date: 24 mar 2014	Rev: 0.7-alpha
KiCad E.D.A. eschema (2013-07-07 BZR 4022)-stable		Id: 6/7



C14, C15, C16 and C17 are 50v X7R Ceramic capacitors.  
 C12 and C13 are 35v Tantalum capacitors.  
 C18 and C19 are 10v Tantalum capacitors.

<b>Git:</b> xxxxxxxxxx		
File: PowerSupplies.sch		
Sheet: /Power Supplies/		
<b>Title:</b> Jaguar PCB for FreeEMS		
Size: A4	Date: 24 mar 2014	<b>Rev:</b> 0.7-alpha
KiCad E.D.A. eeschema (2013-07-07 BZR 4022)-stable		Id: 7/7